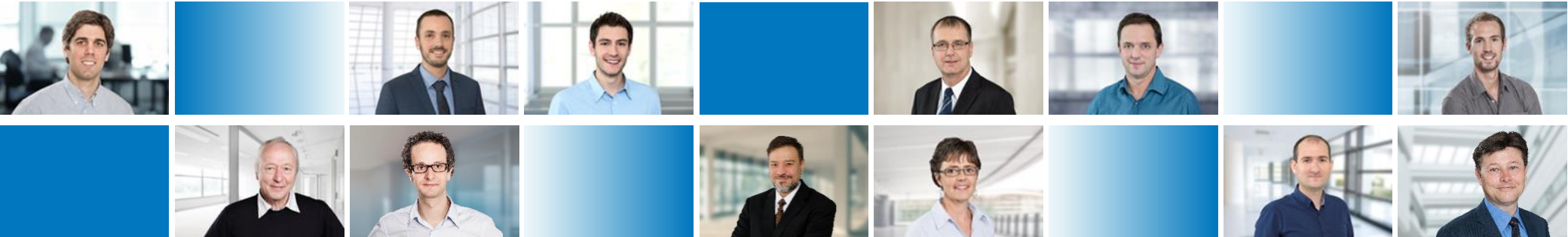


Modelling and Validation Framework for Efficient Development of Consumer Appliances for Mass Production

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Innovation, together we do it

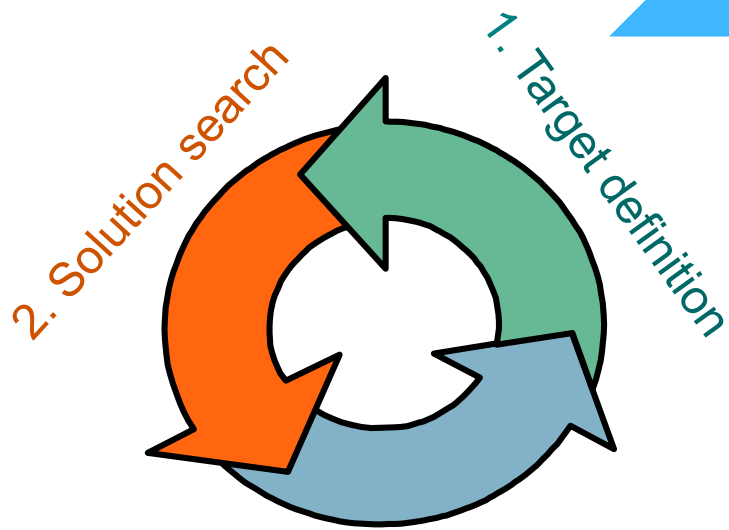
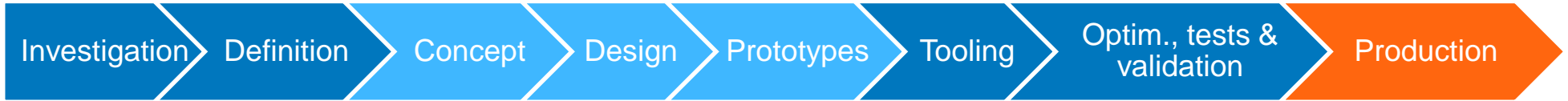
Outline

1. Introduction and Motivation
2. Methodology Blueprint
3. Case Study: DC Motor Controller
4. Conclusions

Introduction: Challenges and Motivation

- Development of consumer appliances is increasing challenging due to:
 - Their growing complexity
 - Strong competition and high customer expectations
 - Requirements for low-costs and tight schedules
 - Challenges related to the mass production
- As the features provided by modern customer appliances heavily rely on embedded systems and software logic, ensuring high-quality embedded software is of paramount importance

Introduction: Development of Consumer Appliances

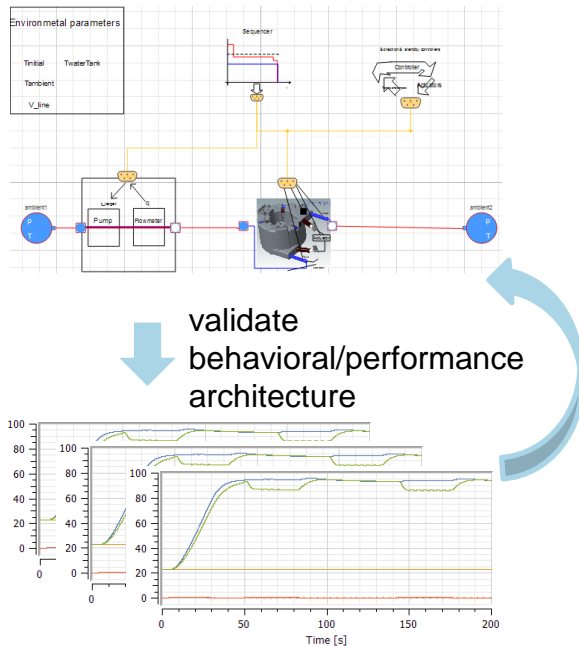


- 3. Selection**
- Experience
 - Prototyping & testing
 - Modeling & simulating

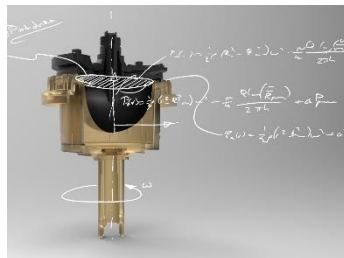
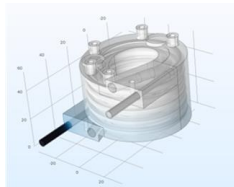


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Introduction: Modelling for Development of Consumer Appliances



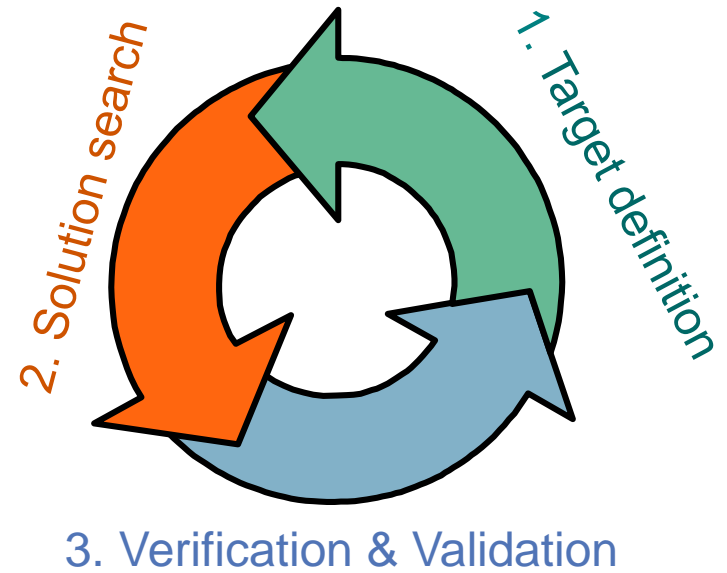
- Modeling & simulating can often represent reality well enough to aid development considerably. In conjunction with prototyping & testing it can be a formidable tool...
 - Risk analysis at an early stage (system architecture at early stages are less costly).
 - Pinpoints weak and strong points of system early on.
 - Optimization of system/components.
 - Qualitative selection of critical tests to be performed on eventual prototype
 - Deep understanding of behavior of the system & reduced likelihood of unexpected behavior/failure.



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Introduction: Embedded SW for Consumer Appliances

- Embedded SW development is an iterative process
- Verifying and Validating the SW on a physical device after each iteration is:
 - Impractical
 - Time-consuming and
 - Sometimes impossible
- SiL: Integration of physical models with software results in a powerful tool to decrease the software validation time and thus to significantly improve the overall efficiency.

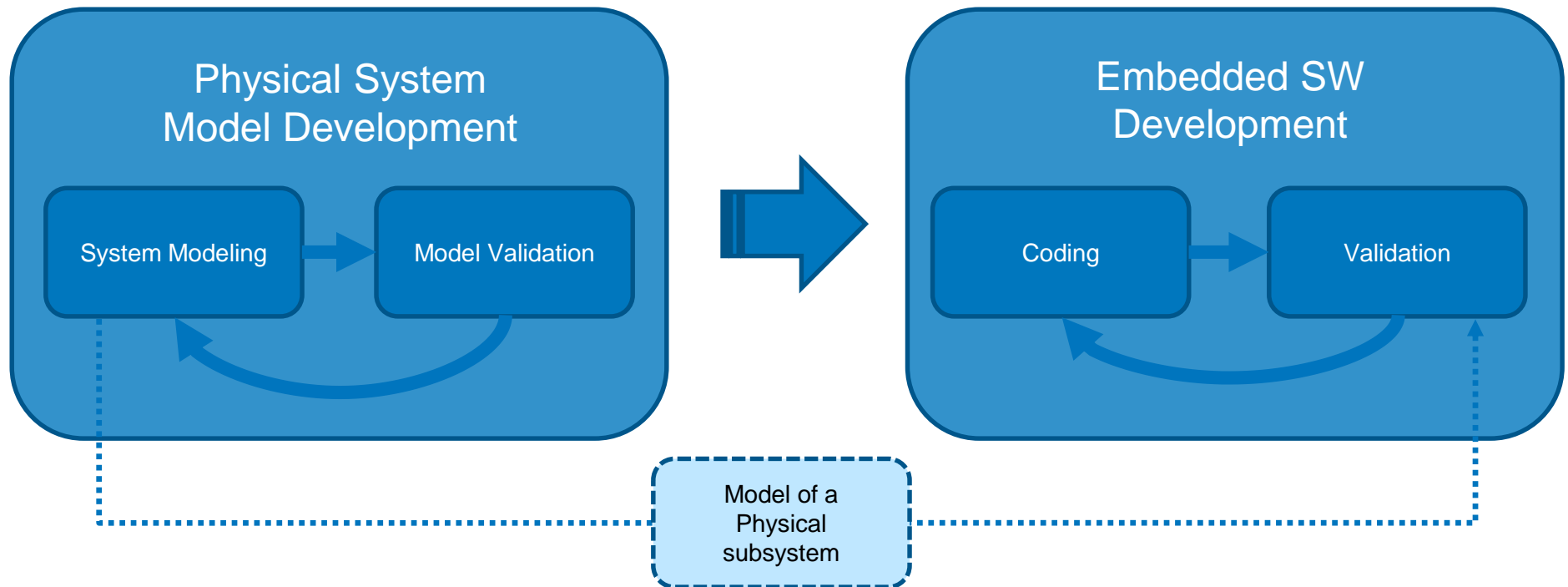


Introduction

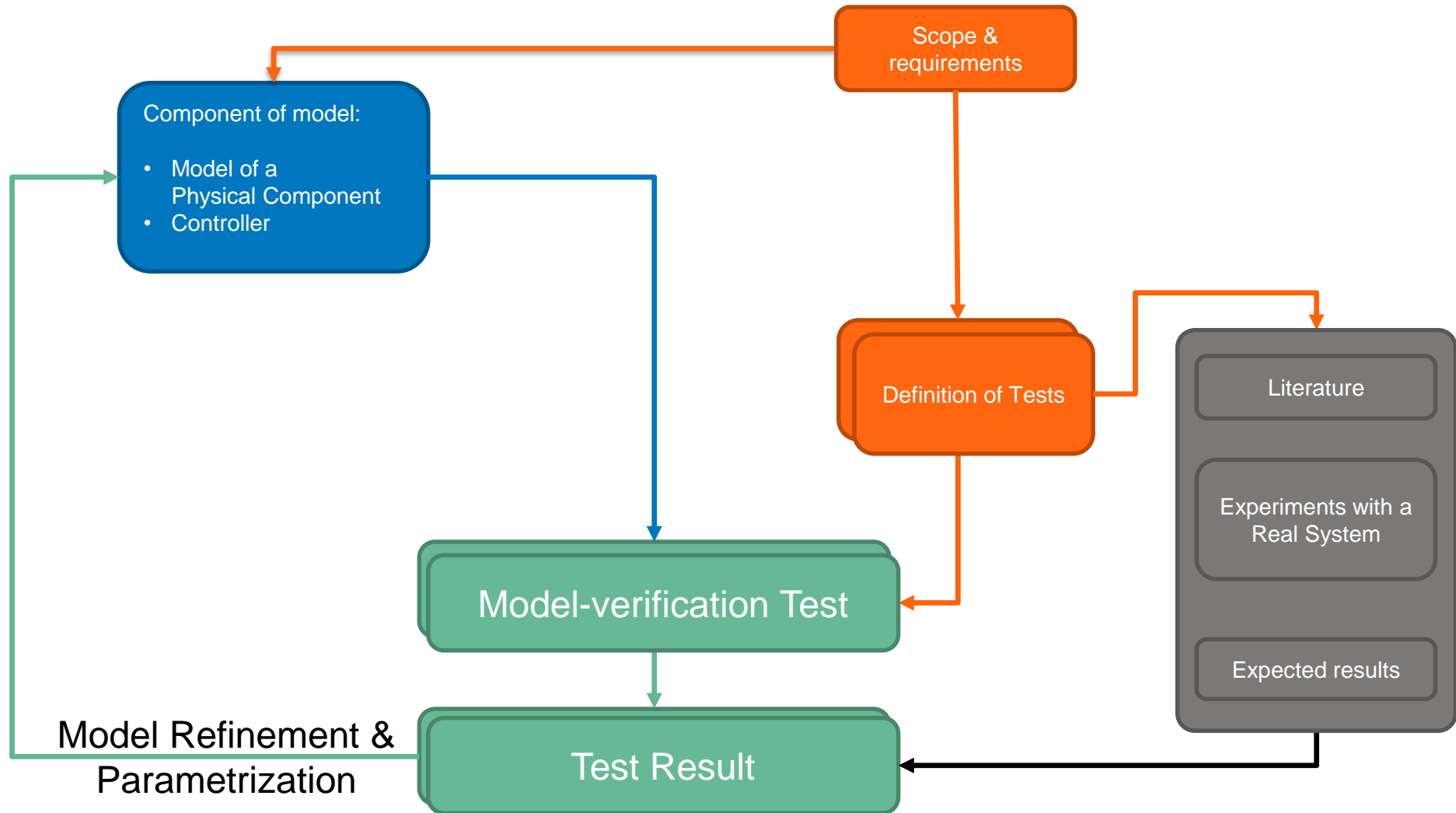
- We have developed a Modelling and Validation Framework to allow:
 - Deep understanding of the system behavior and better risk management
 - Verification of critical sub-systems through parametric modeling.
 - Verification of the embedded software controlling the aforementioned subsystems.

Methodology: Overview

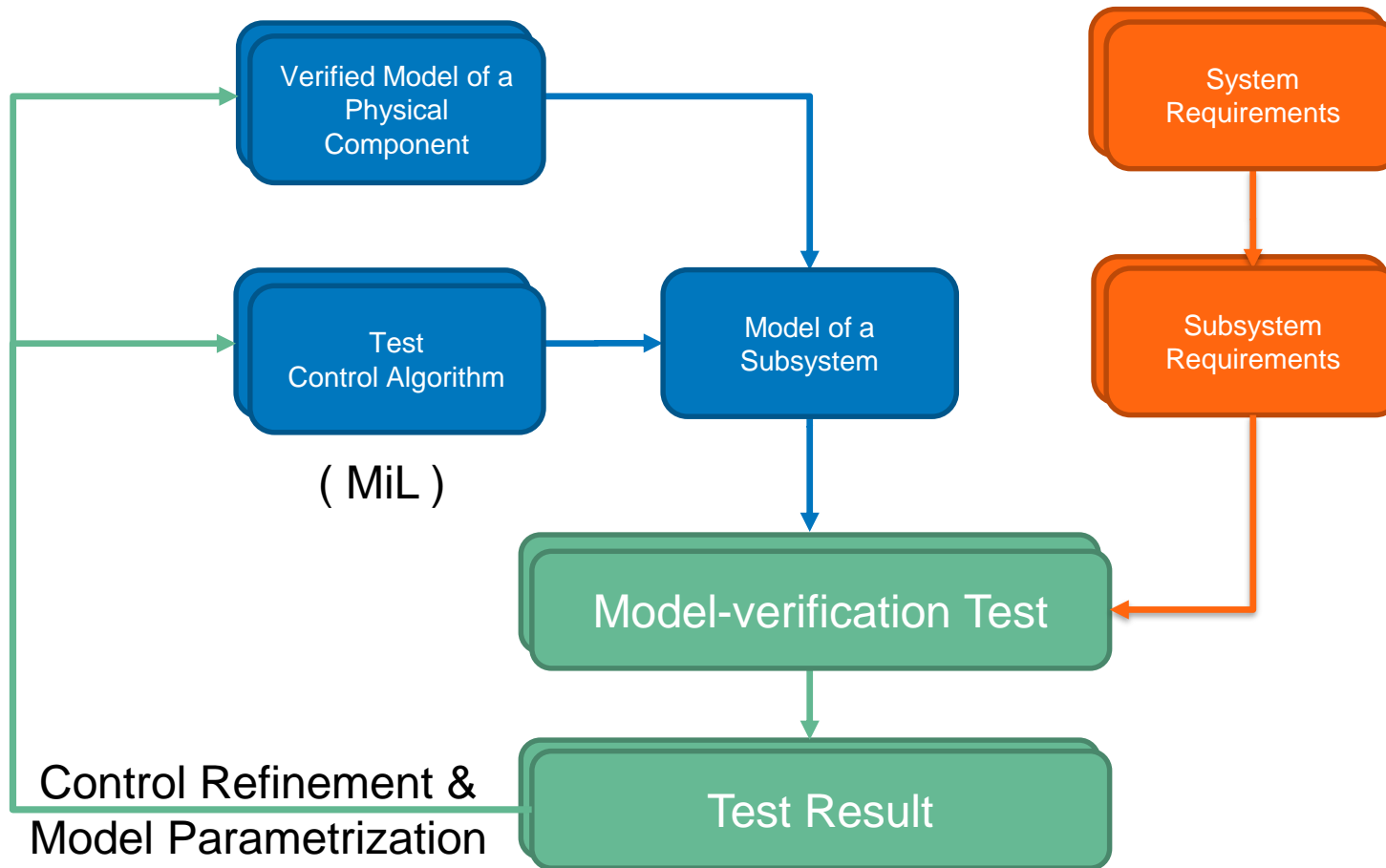
- Modeling of a physical system and its components
- SW development and verification using the model
- Automated SW testing after each SW change



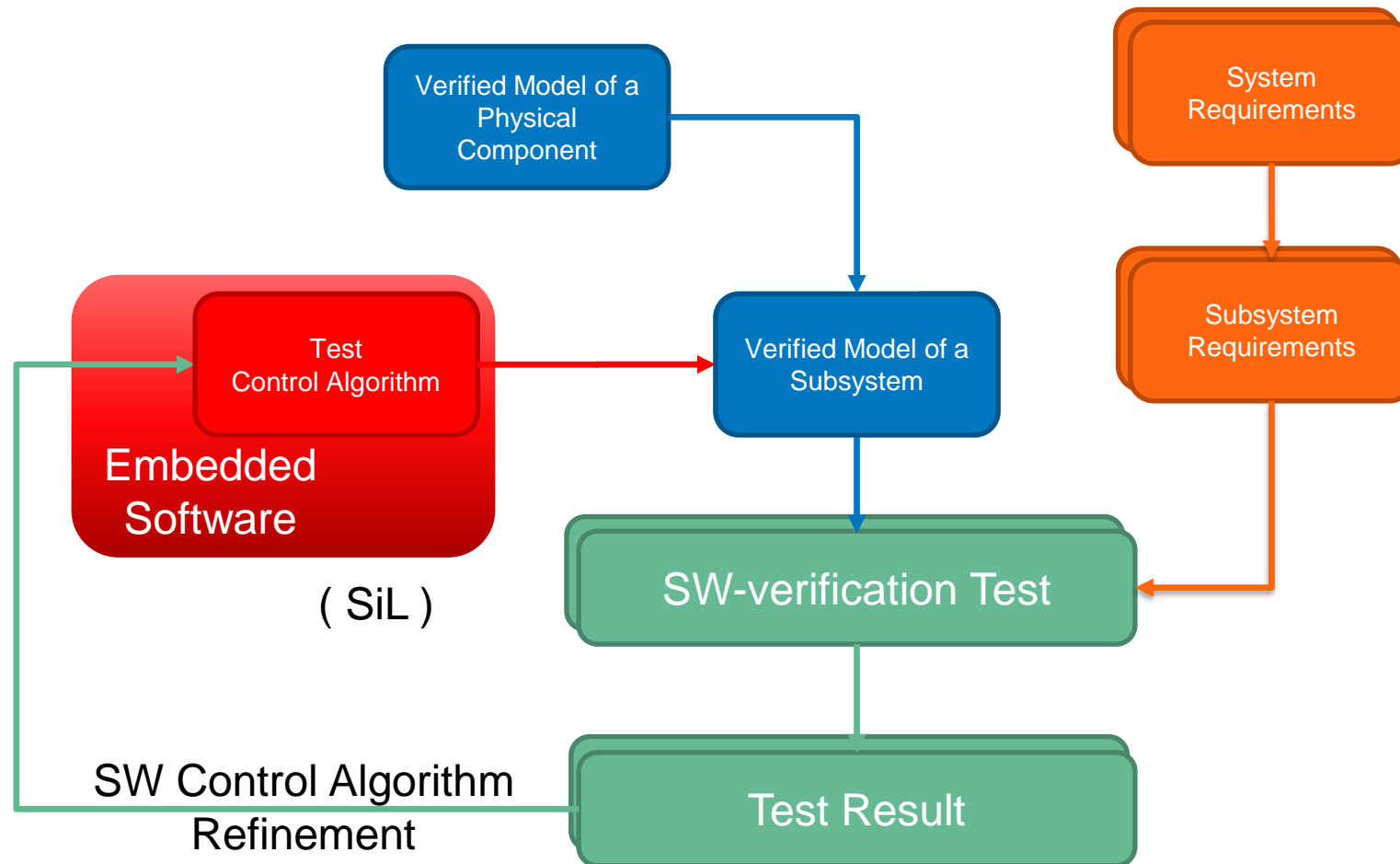
Methodology: Component Modeling



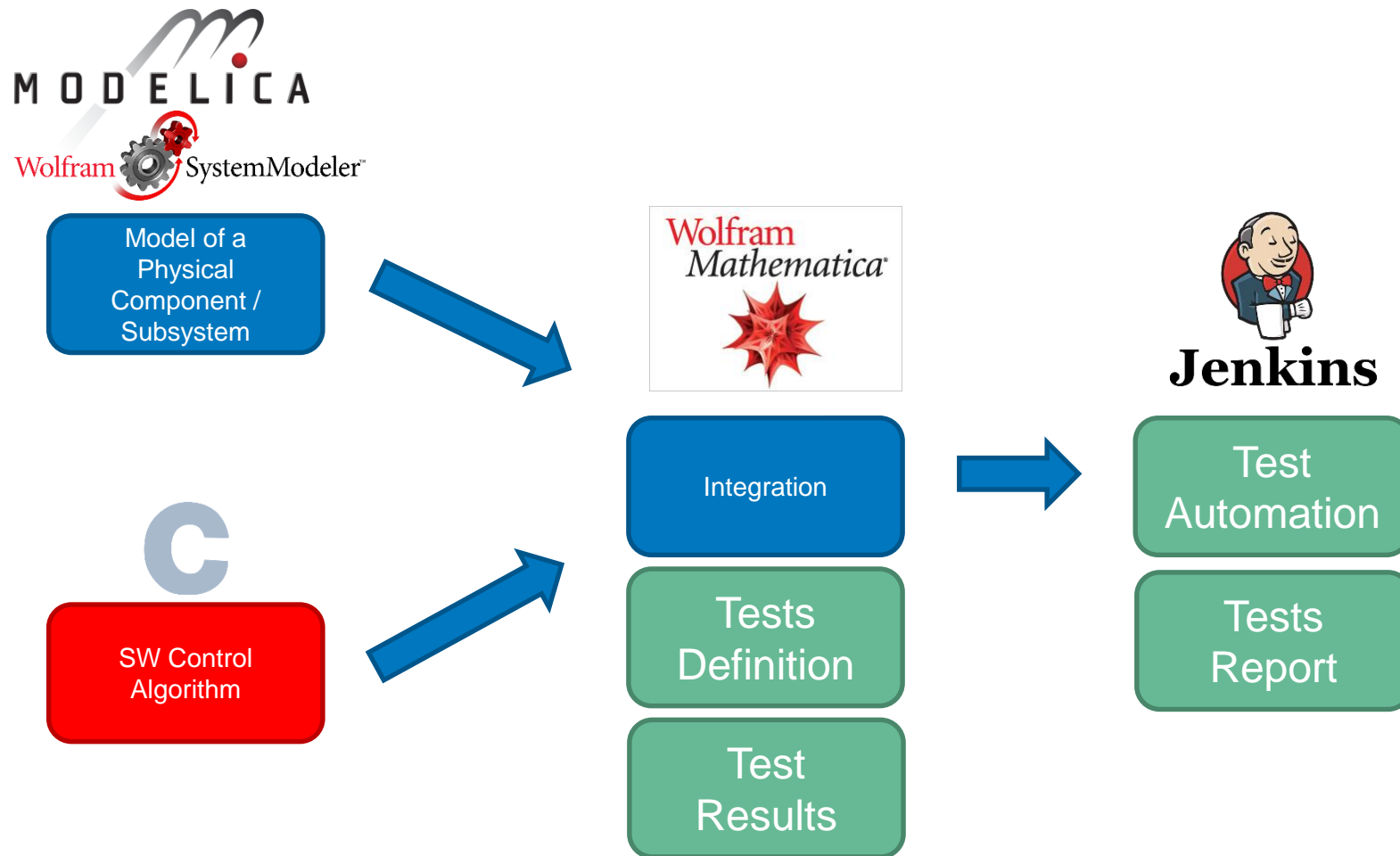
Methodology: Physical System Modeling



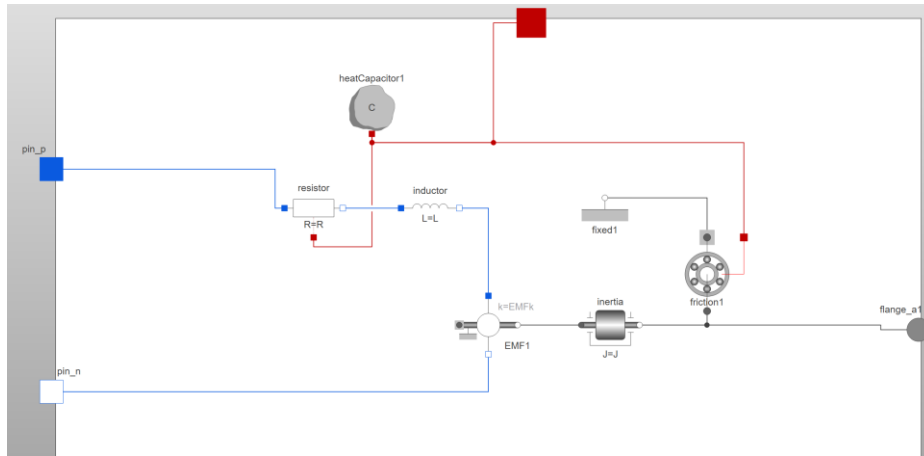
Methodology: SW Development and Verification



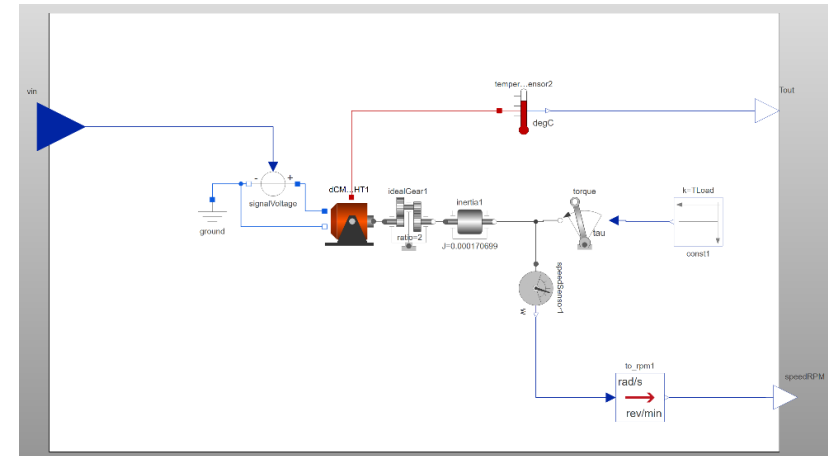
Methodology: Tool Chain



Case Study: DC Motor Controller



DC Motor Model



Subsystem model

Case Study: DC Motor Controller

```

model
sin = SystemModelSimulate[tests.MotorCharacteristicCurve];
speed = sin["mechanicalPowerSensor.relSpeedSensor.u_rel"][[1]];
efficiency = sin["efficiency.y"][[1]];
torque = sin["ramp.y"][[1]];
current = sin["DCMotor_H11.resistor.p.i"][[1]];

data = sin["RawData", {"ramp.y", "mechanicalPowerSensor.relSpeedSensor.u_rel", "DCMotor_H11.resistor.p.i", "efficiency.y"}][All, 1];

workingPoint = (Mean / # (Select[data, Round[#[[1], 0.000] == 0.11 &]])) {1000,  $\frac{60}{2\pi}$ , 1, 100};
stall = (Mean / # (Select[data, Round[#[[2], 1] == 0 && #[[1] > Evaluate@workingPoint[[1]/1000 &]]]) {1000,  $\frac{60}{2\pi}$ , 1, 100};
noLoad = (Mean / # (data[All, Evaluate@Flatten@Position[data[[2]], Max[data[[2]][1]]]) {1000,  $\frac{60}{2\pi}$ , 1, 100};

Evaluate@workingPoint, stall, noLoad}

Expected Output
{{110, 453.024, 0}, {8032, 0, 10670}, {5.564, 22.313, 0.225}, {09.28, 0, 0}}

Test Options
[TestID = "motor model", SameTest = (Norm[#[[1] - #[[1]]] < 30 && Norm[#[[2] - #[[2]]] < 250 && Norm[#[[3] - #[[3]]] < 0.5 && Norm[#[[4] - #[[4]]] < 0.05 &)]
Success

```

```

model
(*[compile source code found within the class *)
dir=#!NameDropSystemModel["DLESystemModeling.Components.PIDs.externalPID4.Utilities.externalFunctions"]["Sourcefile"];
RunProcess[dir->"make.bat", "StandardOutput", ProcessDirectory = dir];

(*[compile and run modelica]
sin = SystemModelSimulate[tests.MotorControllerExternal];
errorTarget = sin["RawData", {"errorWithTarget.y"}];
Table[Max[Select[errorTarget[[1], #[[1] > tmin &]][All, 2]], {tmin, 0.1, 2}]

Expected Output
{100, 30}

Test Options
[TestID = "embedded code controller, ramp up overshoot", SameTest = ( #[[1] < #[[1]] && #[[2] < #[[2]] &)]
Success

```

Tests definition

Test Automation

Jenkins Test Automation interface showing test results for 'wit'.

Test Result : wit

0 failures (±0)

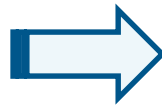
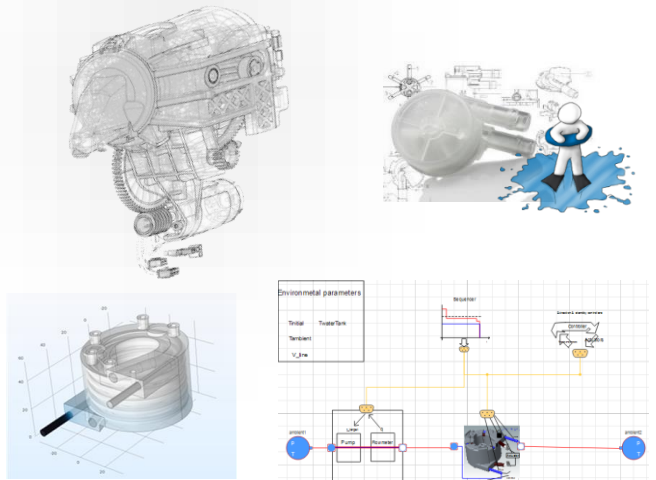
7 tests (±0)
Took 2 min 3 sec.
add description

| Test name | Duration | Status |
|--|----------|--------|
| DLESystemModeling.Library.loaded | 16 sec | Passed |
| Library.loaded | 0.29 sec | Passed |
| Load SystemModeler 5.1 | 37 sec | Passed |
| Modelica.Library.loaded | 0 ms | Passed |
| compiler | 15 ms | Passed |
| embedded_code_controller_ramp_up_overshoot | 26 sec | Passed |
| motor_model | 41 sec | Passed |

Conclusions

- Development of consumer appliances requires systematic application of MBSE through all the stages of the product development, and is aided considerably with system modeling.
- Using our semi-automatized approach to embedded SW development and validation, we can significantly improve our overall efficiency and thus meet the challenge of balancing the time, quality and cost
- Successful application of this approach to a wide range of products has resulted in high-quality consumer appliances and customer satisfaction

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Thank you for your attention!

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